

## Time integration

### Issues

- ▶ Accuracy
- ▶ Cost
  - ▶ CPU = cost/step × #steps,
  - ▶ storage,
  - ▶ programmer's time
- ▶ Stability

Spatial discretisation (typically FE or Spectral)

$$\rightarrow u_t = F(u, t)$$

- ▶ Treat by black-box time-integrator
- ▶ OR recognise spatial structure (typically only for FD)

## Lax equivalence theorem

For a well-posed linear problem,  
a consistent approximation (local error  $\rightarrow 0$  as  $\Delta t \rightarrow 0$ )  
converges to the correct solution  
if and only if the algorithm is stable

## Stability in time

1. Unstable algorithm – bad!  
– numerics blow up all  $\Delta t$ , usually rapidly, often oscillates
2. Conditionally stable – normal  
– stable if  $\Delta t$  not too big
3. Unconditionally stable – slightly dangerous  
– stable all  $\Delta t$ , inaccurate large  $\Delta t$

'Stable' = ?

- (i) numerics decays, even if physics does not
- (ii) numerics do not blow up for all  $t$
- (iii) numerics do not blow up much, i.e. converge fixed  $t$   
e.g. need  $\Delta t < a + b/t$

## Stiffness, for $u_t = F(u, t)$

How do small disturbances grow/decay?

Linearise + freeze coefficients – occasionally wrong

$$\delta u_t = F'(u_0, t_0) \delta u$$

Find eigenvalues  $\lambda$  of  $F'(u_0, t_0)$

Stiff if  $\lambda_{\max} \gg \lambda_{\min}$ , typically by  $10^4$

Stability controlled by largest  $|\lambda|$ , need

$$\Delta t < \frac{\text{const}}{|\lambda|_{\max}}$$

– may represent boring time behaviour on fine scales  
If so, use unconditionally stable algorithm with big  $\Delta t$  and  
inaccurate rendering of boring fine details

## Forward Euler – 1st order, explicit

For  $u_t = \lambda u$

$$\frac{u^{n+1} - u^n}{\Delta t} = \lambda u^n$$

Hence

$$u^{n+1} = (1 + \lambda \Delta t)^{n=t/\Delta t} u^1 \\ \rightarrow e^{\lambda t} u^1 \quad \text{as } \Delta t \rightarrow 0$$

Case  $\lambda$  real and negative: stable if  $\Delta t < \frac{2}{|\lambda|}$

Case  $\lambda$  purely imaginary

$$|1 + \lambda \Delta t| = (1 + |\lambda|^2 \Delta t^2)^{1/2} > 1 \quad \text{all } \Delta t$$

so “unstable”

Now

$$(1 + |\lambda|^2 \Delta t^2)^{t/2\Delta t} \xrightarrow{\Delta t \rightarrow 0} e^{\frac{1}{2}|\lambda|^2 \Delta t t}$$

i.e. does not blow up much ( $\epsilon$ ) if

$$\Delta t < \frac{2 \ln \epsilon}{\lambda^2 t}$$

## Crank-Nicolson – 2nd order implicit

For  $u_t = \lambda u$

$$\frac{u^{n+1} - u^n}{\Delta t} = \lambda \frac{u^{n+1} + u^n}{2}$$

NB: RHS uses unknown  $u^{n+1}$ , not a problem for this simple linear problem. Solution

$$u^n = \left( \frac{1 + \frac{1}{2}\lambda\Delta t}{1 - \frac{1}{2}\lambda\Delta t} \right)^n u^0$$

Case  $Re(\lambda) < 0$  stable all  $\Delta t$

Case  $\lambda$  imaginary amplitude correctly constant all  $\Delta t$  although phase drifts

## Backward Euler – 1st order, implicit

For  $u_t = \lambda u$

$$\frac{u^{n+1} - u^n}{\Delta t} = \lambda u^{n+1}$$

So

$$u^n = \left( \frac{1}{1 - \lambda \Delta t} \right)^n u_0$$

Very stable just unstable in  $|1 - \lambda \Delta t| < 1$

But inaccurate if  $\Delta t$  large

E.g.  $\lambda$  real and negative & large  $\Delta t = 1/|\lambda|$  gives

$$u(t) \sim e^{\lambda t \ln 2} \quad \text{cf } e^{\lambda t}$$

## Leap frog - 2nd order, explicit

$$\frac{u^{n+1} - u^{n-1}}{2\Delta t} = \lambda u^n$$

Two-term recurrence relation

$$u^{n+1} - 2\lambda\Delta t u^n - u^{n-1} = 0$$

has solutions  $u^n = A\theta_+^n + B\theta_-^n$  with  $\theta_{\pm} = \lambda\Delta t \pm \sqrt{1 + \lambda^2\Delta t^2}$

So

$$u^n \sim e^{\lambda n\Delta t} + \epsilon(-1)^n e^{-\lambda n\Delta t}$$

**Spurious solution** blows up if  $\text{Re}(\lambda) < 0$

**But stable** for purely imaginary  $\lambda$  &  $\Delta t < 1/|\lambda|$

## Runge-Kutta

E.g. standard 4th order RK, for  $u_t = F(u, t)$

$$du^1 = \Delta t F(u^n, t^n)$$

$$du^2 = \Delta t F(u^n + \frac{1}{2}du^1, t^n + \frac{1}{2}\Delta t)$$

$$du^3 = \Delta t F(u^n + \frac{1}{2}du^2, t^n + \frac{1}{2}\Delta t)$$

$$du^4 = \Delta t F(u^n + du^3, t^n + \Delta t)$$

$$u^{n+1} = u^n + \frac{1}{6}(du^1 + 2du^2 + 2du^3 + du^4)$$

NB: 4 function calls per step – very expensive

Can vary  $\Delta t$  after each step – adaptive

Good stability, need  $\Delta t \lesssim \frac{3}{|\lambda|}$

## Error control for RK4

Take 2 steps of  $\Delta t$  from  $u^n$

$$u^{n+2} = A + 2b\Delta t^5 + \dots$$

Take 1 step of  $2\Delta t$  from  $u^n$

$$u^* = A + b(2\Delta t)^5 + \dots$$

Extrapolating, 5th order estimate of answer

$$\frac{16}{15}u^{n+2} - \frac{1}{15}u^*$$

Estimate of error

$$\frac{1}{30}(u^* - u^{n+2})$$

– decide if to decrease/increase  $\Delta t$

## Implicit Runge-Kutta

$$du^1 = \Delta t F\left(u^n + \frac{1}{4}du^1 + \left(\frac{1}{4} - \frac{\sqrt{3}}{6}\right)du^2, t^n + \left(\frac{4}{1} - \frac{\sqrt{3}}{6}\right)\Delta t\right)$$

$$du^2 = \Delta t F\left(u^n + \left(\frac{1}{4} + \frac{\sqrt{3}}{6}\right)du^1 + \frac{1}{4}du^2, t^n + \left(\frac{1}{4} + \frac{\sqrt{3}}{6}\right)\Delta t\right)$$

$$u^{n+1} = u^n + \frac{1}{2}du^1 + \frac{1}{2}du^2$$

Iterate to find  $du^1$  and  $du^2$  – **very expensive**

**Stable** all  $\Delta t$  if  $\text{Re}(\lambda) \leq 0$

## Multi-step methods – use information from previous steps

AB3 Adams-Bashforth, 3rd order, explicit

$$u^{n+1} = u^n + \frac{\Delta t}{12} (23F_n - 16F_{n-1} + 5F_{n-2})$$

AM4 Adams-Moulton, 4th order, implicit

$$u^{n+1} = u^n + \frac{\Delta t}{24} (9F_{n+1} + 19F_n - 5F_{n-1} + F_{n-2})$$

NB uses 1 function evaluation per step – good

NB difficult to start or change step size  $\Delta t$  – bad

NB Stable  $\Delta t \lesssim 1/|\lambda|$

Predictor-corrector

AB3 sufficiently good estimate for  $u^{n+1}$  to use in AM4  $F_{n+1}$ ,  
but then 2 function evaluations per step

## Navier-Stokes – different methods for different terms

For  $u_t + uu_x = u_{xx}$  (no pressure, yet)

$$\frac{u^{n+1} - u^n}{\Delta t} = - (uu_x)^{n+\frac{1}{2}} + \frac{u_{i+1}^{n+1} - 2u_i^{n+1} + u_{i-1}^{n+1} + u_{i+1}^n - 2u_i^n + u_{i-1}^n}{2\Delta x^2}$$

implicit on diffusion for stability at boring fine scales

AB3 explicit on safe advection

$$(uu_x)^{n+\frac{1}{2}} = \frac{1}{12} \left( 23(uu_x)^{n-\frac{1}{2}} - 16(uu_x)^{n-\frac{3}{2}} + 5(uu_x)^{n-\frac{5}{2}} \right)$$

Iserles Zig-Zag – 2nd order and sort of upwinding

$$(uu_x)^{n+\frac{1}{2}} = \frac{u_{i+1}^{n+1} + u_i^n}{2} \left( \frac{u_{i+1}^{n+1} - u_i^{n+1}}{2\Delta x} + \frac{u_i^n - u_{i-1}^n}{2\Delta x} \right) \quad \text{if } u_i^n > 0$$

Lagrangian methods in  $\mathbf{u} \cdot \nabla \mathbf{u}$  dominant

## Symplectic integrators

For Hamiltonian (non-dissipative) systems

$$\dot{p}_i = -\frac{\partial H}{\partial q_i}, \quad \dot{q}_i = \frac{\partial H}{\partial p_i}$$

conserve  $H$  and projections of volume of phase-space

NB Important for integration to long times.

Symplectic integrators have same conservations properties for a numerical approximation to the Hamiltonian  $H^{\text{num}}(\Delta t)$

NB must keep  $\Delta t$  fixed

E.g. Störmer-Verlet (sort of leap-frog) – for molecular dynamics

$$\begin{aligned} p^{n+\frac{1}{2}} &= p^n + \frac{1}{2}\Delta t F(r^n) \\ r^{n+1} &= r^n + \Delta t \frac{1}{m} p^{n+\frac{1}{2}} \\ p^{n+1} &= p^{n+\frac{1}{2}} + \frac{1}{2}\Delta t F(r^{n+1}) \end{aligned}$$

## Pressure update - 2nd order, exact projection to $\nabla \cdot \mathbf{u} = 0$

Split time-step

$$\frac{u^* - u^n}{\Delta t} = - (uu_x)^{n+\frac{1}{2}} - \nabla p^{n-\frac{1}{2}} + \nu \nabla^2 \left( \frac{u^* + u^n}{2} \right)$$

Projection

$$u^{n+1} = u^* + \Delta t \nabla \phi^{n+1}$$

with

$$\nabla^2 \phi^{n+1} = -\nabla \cdot u^* / \Delta t \quad \text{with BC} \quad \Delta t \frac{\partial \phi^{n+1}}{\partial n} = u_n^{\text{BC}} - u_n^*$$

Update

$$\nabla p^{n+\frac{1}{2}} = \nabla p^{n-\frac{1}{2}} - \nabla \left( \phi^{n+1} - \frac{1}{2}\nu \Delta t \nabla^2 \phi^{n+1} \right)$$

Tangential BC

$$u_{\text{tang}}^* = u_{\text{tang}}^{\text{BC}} - \Delta t \nabla \phi^n$$