

Last time – Finite Elements, part 1

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2. Variational Statement

$$\nabla^2 f = \rho \quad \equiv \quad \delta I = 0, \quad I = \int \frac{1}{2} |\nabla f|^2 + \rho f$$

so

$$K_{ij} f_j = r_i$$

with

$$K_{ij} = \int \nabla \phi_i \cdot \nabla \phi_j \quad r_i = \int \rho \phi_i$$

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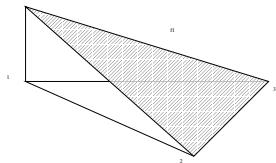
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This time – Finite Elements, part 2

Details in 2D with linear triangular elements

Consider one triangle

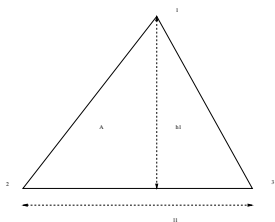
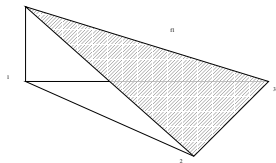
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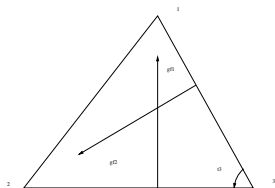
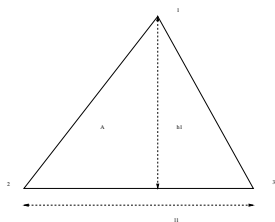
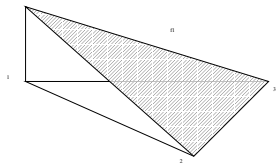


$$K_{11} = \int \nabla\phi_1 \cdot \nabla\phi_1 = \frac{A}{h_1^2}$$

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$$K_{11} = \int \nabla\phi_1 \cdot \nabla\phi_1 = \frac{A}{h_1^2}$$

$$K_{12} = \int \nabla\phi_1 \cdot \nabla\phi_2 = -\frac{A \cos \theta_3}{h_1 h_2}$$

further manipulations

$$h_1 = l_2 \sin \theta_3 \quad \text{and} \quad h_2 = l_1 \sin \theta_3.$$

and

$$A = \frac{1}{2} l_1 l_2 \sin \theta_3.$$

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$$K_{12} = -\frac{\cos \theta_3 A}{h_1 h_2} = -\frac{1}{2} \cot \theta_3.$$

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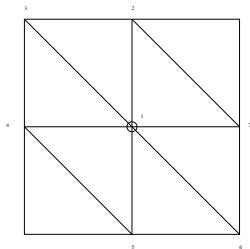
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Because

$$\nabla \phi_1 \cdot \nabla (\phi_1 + \phi_2 + \phi_3 \equiv 1) \equiv 0.$$

Assembling contributions from different triangles

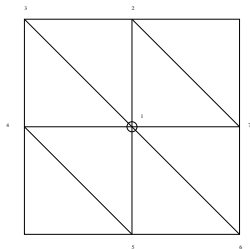
Special grid:



For the 123-triangle,

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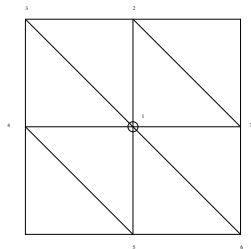
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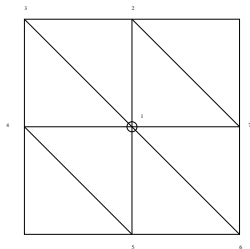
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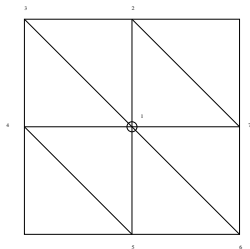
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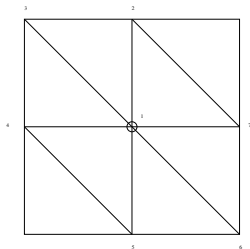


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Assembling from all triangles

$$K_{11} = 4, \quad K_{12} = K_{14} = K_{15} = K_{17} = -1, \quad K_{13} = K_{16} = 0.$$

Forcing

$$r_i = \int \rho \phi_i = \frac{1}{3} A \rho_i$$

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On more general **unstructured grids** need

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Can use list of triangles to assemble sparse matrix K_{ij} .

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Require **residual** to be OG all **N** basis functions

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i.e.

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part of Navier-Stokes

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i.e.

$$M_{ij} \dot{u}_i = -K_{ij} u_i$$

with 'Mass' $M_{ij} = \langle \phi_i, \phi_j \rangle$ and 'Stiffness' $K_{ij} = \langle \nabla \phi_i, \nabla \phi_j \rangle$

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Using linear elements on equal intervals h

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$$M_{ij} = \begin{cases} \frac{2}{3}h & i = j \\ \frac{1}{6}h & i = j \pm 1 \\ 0 & \text{otherwise} \end{cases} \quad \text{and} \quad K_{ij} = \begin{cases} 2/h & i = j \\ -1/h & i = j \pm 1 \\ 0 & \text{otherwise} \end{cases}$$

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Hence

$$h \left(\frac{1}{6} \dot{u}_{i-1} + \frac{2}{3} \dot{u}_i + \frac{1}{6} \dot{u}_{i+1} \right) = \frac{1}{h} (u_{i-1} - 2u_i + u_{i+1}).$$

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Remark Linear algebra to find \dot{u}_i – tridiagonal matrix fast to invert
Remark Time step this “semi-discretised” form with any FD (NOT FE) algorithm, e.g.

$$u_i^{n+1} = u_i^n + \Delta t \dot{u}_i$$

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Assemble contributions to M and K from different triangles

$$M_{ij} = \begin{cases} \frac{1}{12} h^2 & i = j \\ \frac{1}{24} h^2 & i \neq j, \end{cases} \quad K_{ij} \text{ as before}$$

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So

$$\frac{1}{2}h^2 \left(\dot{u}_1 + \frac{1}{6}(\dot{u}_2 + \dot{u}_3 + \dot{u}_4 + \dot{u}_5 + \dot{u}_6 + \dot{u}_7) \right) = u_2 + u_4 + u_5 + u_7 - 4u_1$$

with linear problem to find \dot{u}_i

Navier-Stokes

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a. Weak formulation

Use FE representation

$$\mathbf{u}(\mathbf{x}, t) = \sum_i \mathbf{u}_i(t) \phi_i(\mathbf{x}),$$

$$p(\mathbf{x}, t) = \sum_i p_i(t) \psi_i(\mathbf{x}),$$

Need different ϕ_i and ψ_i .

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Galerkin

$$\left\langle \rho \left(\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} \right) + \nabla p - \mu \nabla^2 \mathbf{u}, \phi_j \right\rangle = 0 \quad \text{all } \phi_j,$$

and incompressibility constraint

$$\langle \nabla \cdot \mathbf{u}, \psi_j \rangle = 0 \quad \text{all } \psi_j.$$

Integration by parts

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$$\rho (M_{ij} \dot{\mathbf{u}}_j + Q_{ijk} \mathbf{u}_j \mathbf{u}_k) = -B_{ji} p_j - \mu K_{ij} \mathbf{u}_j,$$

and

$$-B_{ij} \mathbf{u}_j = 0,$$

with mass M and stiffness K as before, and two new coupling matrices

$$Q_{ijk} = \langle \phi_i \nabla \phi_j, \phi_k \rangle \quad \text{and} \quad B_{ij} = \langle \nabla \psi_i, \phi_j \rangle = -\langle \psi_i, \nabla \phi_j \rangle.$$

b. Time integration

Time step semi-discretised form with any FD algorithm

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Incompressible by [projection split step](#)

$$\begin{aligned}\mathbf{u}^* &= \mathbf{u}_i^n + \Delta t (\dot{\mathbf{u}}_i^n \text{ without the } p \text{ term}), \\ \mathbf{u}^{n+1} &= \mathbf{u}^* + \Delta t (\dot{\mathbf{u}}_i^n \text{ with just the } p \text{ term}),\end{aligned}$$

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with p chosen so the incompressibility at the end of the step

$$B\mathbf{u}^{n+1} = 0.$$

Problems with pressure – Locking

Consider triangles with velocity linear and pressure constant

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Then

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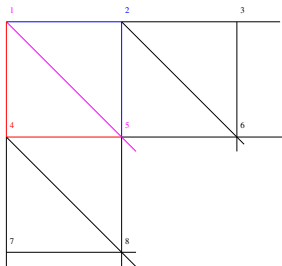
gives

$$\oint_{\Delta_j} u_n = 0,$$

i.e. no net volume flux out of triangle Δ_j .

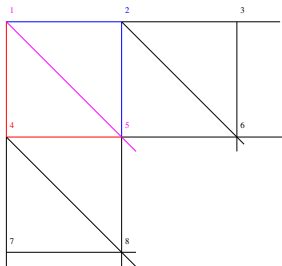
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Consider top corner, with $\mathbf{u} = 0$ on boundary (74123).



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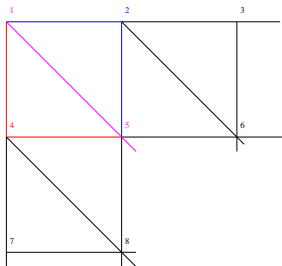
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For triangle 145,

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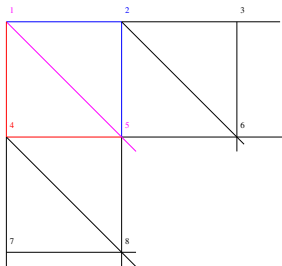
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flux in over edge 45 is $\frac{1}{2} h v_5$,

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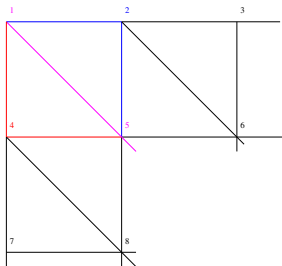


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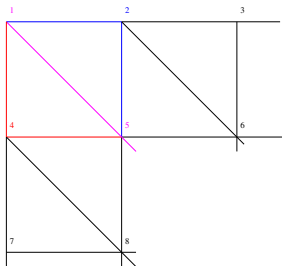
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Hence $u_5 = 0$,

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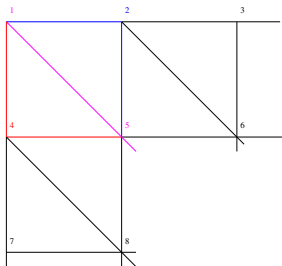
For triangle 145,

flux in over edge 45 is $\frac{1}{2} h v_5$, flux out over edge 15 is $\frac{1}{2} h (u_5 + v_5)$

Hence $u_5 = 0$, by symmetry (triangle 125) $v_5 = 0$.

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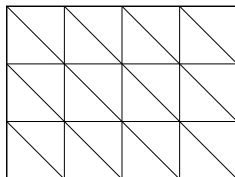
Then $\mathbf{u}_6 = 0$ and $\mathbf{u}_8 = 0$, so $\mathbf{u} \equiv 0$.

... locking

For one triangle there are $1p + 3u + 3v$ variables.

... locking

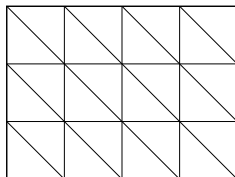
For one triangle there are $1p + 3u + 3v$ variables.
But on a 4×3 grid



there are $24p + 6u + 6v$ variables.

... locking

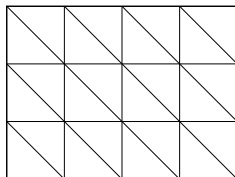
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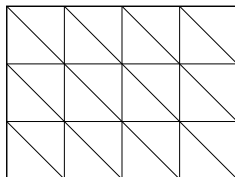
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Create more u & v with bubble functions (vanish on boundaries of elements),

... locking

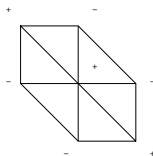
For one triangle there are $1p + 3u + 3v$ variables.
But on a 4×3 grid



there are $24p + 6u + 6v$ variables. Too many p
Create more u & v with bubble functions (vanish on boundaries of elements), or reduce number of pressure

Spurious pressure modes

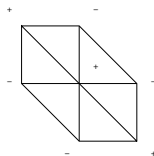
if have p linear over triangle



As in Algorithm 2 of driven cavity, above pressure drives no flow

Spurious pressure modes

if have p linear over triangle



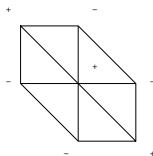
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$$B_{jj} p_j = 0.$$

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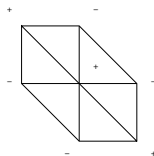
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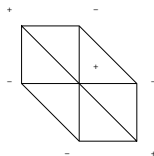
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Alternatively, replace incompressibility by

$$\nabla \cdot \mathbf{u} = \beta h^2 p, \quad \text{with optimal } \beta = 0.025$$

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Weak formulation

$$B_{ij}\mathbf{u}_j + \beta h^2 p_i = 0.$$

Also upwinding

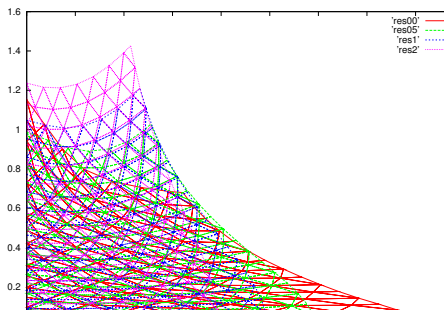
- ▶ Petrov-Galerkin: Add upstream bias to weight functions,

Also upwinding

- ▶ Petrov-Galerkin: Add upstream bias to weight functions, but adds artificial numerical streamwise diffusion

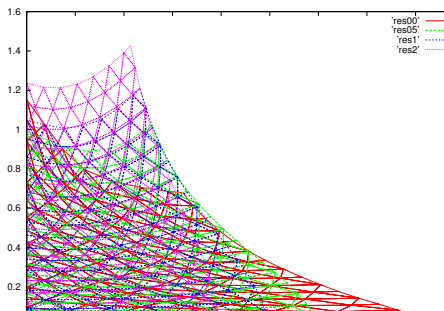
Also upwinding

- ▶ Petrov-Galerkin: Add upstream bias to weight functions, but adds artificial numerical streamwise diffusion
- ▶ Lagrangian Finite Elements – elements advected with flow,



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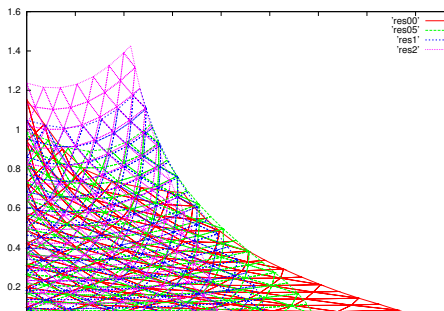
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but elements become distorted

Also upwinding

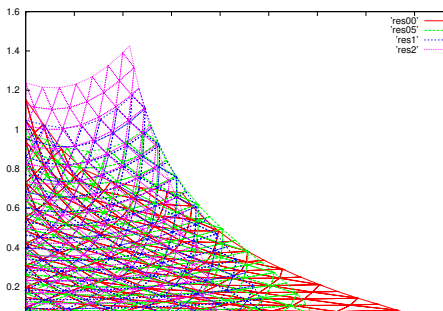
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but elements become distorted
→ re-gridding

Also upwinding

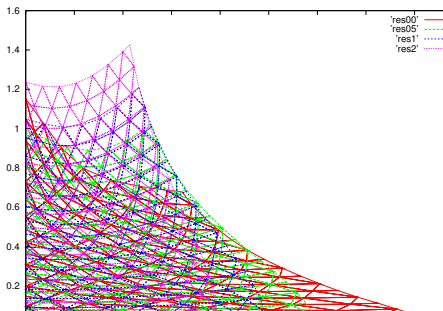
- ▶ Petrov-Galerkin: Add upstream bias to weight functions, but adds artificial numerical streamwise diffusion
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→ re-gridding, e.g. diagonal swapping.

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- ▶ Lagrangian Finite Elements – elements advected with flow,



but elements become distorted

→ re-gridding, e.g. diagonal swapping.

- ▶ ALE – somewhere between Lagrangian and Eulerian.