

Resumé of Part 1

Solve driven cavity at $Re = 10$

Physics, maths of PDE

$\psi - \omega$ and $u - v - p$ formulations: Pressure

Finite Differences

Poisson solver, SOR

Time stepping, numerical instability

Accuracy, no bugs?, results

Resumé of Part 1

Solve driven cavity at $Re = 10$

Physics, maths of PDE

$\psi - \omega$ and $u - v - p$ formulations: Pressure

Finite Differences

Poisson solver, SOR

Time stepping, numerical instability

Accuracy, no bugs?, results

Part II – more details on general issues

Discretisation – FD, FE, Spectral

Time-stepping – implicit, pressure

Solving large sparse linear equations

Part III – collection of special topics

Finite Differences

Higher order derivatives

a. central differencing

With $O(\Delta x^2)$ errors

$$f'_i = \frac{f_{i+1} - f_{i-1}}{2\Delta x}$$
$$f''_i = \frac{f_{i+1} - 2f_i + f_{i-1}}{\Delta x^2}$$

Finite Differences

Higher order derivatives

a. central differencing

With $O(\Delta x^2)$ errors

$$f'_i = \frac{f_{i+1} - f_{i-1}}{2\Delta x}$$
$$f''_i = \frac{f_{i+1} - 2f_i + f_{i-1}}{\Delta x^2}$$

and higher order derivatives

$$f'''_i = \frac{f''_{i+1} - f''_{i-1}}{2\Delta x}$$

Finite Differences

Higher order derivatives

a. central differencing

With $O(\Delta x^2)$ errors

$$f'_i = \frac{f_{i+1} - f_{i-1}}{2\Delta x}$$
$$f''_i = \frac{f_{i+1} - 2f_i + f_{i-1}}{\Delta x^2}$$

and higher order derivatives

$$f'''_i = \frac{f''_{i+1} - f''_{i-1}}{2\Delta x}$$
$$= \frac{f_{i+2} - 2f_{i+1} + 2f_{i-1} - f_{i-2}}{2\Delta x^3}$$

Finite Differences

Higher order derivatives

a. central differencing

With $O(\Delta x^2)$ errors

$$f'_i = \frac{f_{i+1} - f_{i-1}}{2\Delta x}$$
$$f''_i = \frac{f_{i+1} - 2f_i + f_{i-1}}{\Delta x^2}$$

and higher order derivatives

$$f'''_i = \frac{f''_{i+1} - f''_{i-1}}{2\Delta x}$$
$$= \frac{f_{i+2} - 2f_{i+1} + 2f_{i-1} - f_{i-2}}{2\Delta x^3}$$
$$f''''_i = \frac{f''_{i+1} - 2f''_i + f''_{i-1}}{\Delta x^2}$$

Finite Differences

Higher order derivatives

a. central differencing

With $O(\Delta x^2)$ errors

$$f'_i = \frac{f_{i+1} - f_{i-1}}{2\Delta x}$$
$$f''_i = \frac{f_{i+1} - 2f_i + f_{i-1}}{\Delta x^2}$$

and higher order derivatives

$$f'''_i = \frac{f''_{i+1} - f''_{i-1}}{2\Delta x}$$
$$= \frac{f_{i+2} - 2f_{i+1} + 2f_{i-1} - f_{i-2}}{2\Delta x^3}$$
$$f''''_i = \frac{f''_{i+1} - 2f''_i + f''_{i-1}}{\Delta x^2}$$
$$= \frac{f_{i+2} - 4f_{i+1} + 6f_i - 4f_{i-1} + f_{i-2}}{\Delta x^4}$$

even \rightarrow Pascal Δ , odd $\rightarrow 2 \times$ Pascal with shift

Error analysis by Taylor series

$$f_{i+1} = f(x = i\Delta x + \Delta x)$$

Error analysis by Taylor series

$$\begin{aligned}f_{i+1} &= f(x = i\Delta x + \Delta x) \\ &= f_i + \Delta x f'_i + \frac{1}{2}\Delta x^2 f''_i + \frac{1}{6}\Delta x^3 f'''_i + \frac{1}{24}\Delta x^4 f''''_i + \dots\end{aligned}$$

Error analysis by Taylor series

$$\begin{aligned}f_{i+1} &= f(x = i\Delta x + \Delta x) \\ &= f_i + \Delta x f'_i + \frac{1}{2}\Delta x^2 f''_i + \frac{1}{6}\Delta x^3 f'''_i + \frac{1}{24}\Delta x^4 f''''_i + \dots\end{aligned}$$

Then

$$f_{i+1} - f_{i-1} = 2\Delta x f'_i + \frac{1}{3}\Delta x^3 f'''_i + O(\Delta x^5).$$

Error analysis by Taylor series

$$\begin{aligned}f_{i+1} &= f(x = i\Delta x + \Delta x) \\ &= f_i + \Delta x f'_i + \frac{1}{2}\Delta x^2 f''_i + \frac{1}{6}\Delta x^3 f'''_i + \frac{1}{24}\Delta x^4 f''''_i + \dots\end{aligned}$$

Then

$$f_{i+1} - f_{i-1} = 2\Delta x f'_i + \frac{1}{3}\Delta x^3 f'''_i + O(\Delta x^5).$$

But have f'''_i to second order. Substitute for

Error analysis by Taylor series

$$\begin{aligned}f_{i+1} &= f(x = i\Delta x + \Delta x) \\ &= f_i + \Delta x f'_i + \frac{1}{2}\Delta x^2 f''_i + \frac{1}{6}\Delta x^3 f'''_i + \frac{1}{24}\Delta x^4 f''''_i + \dots\end{aligned}$$

Then

$$f_{i+1} - f_{i-1} = 2\Delta x f'_i + \frac{1}{3}\Delta x^3 f'''_i + O(\Delta x^5).$$

But have f'''_i to second order. Substitute for

$$f'_i = \frac{-\frac{1}{12}f_{i+2} + \frac{2}{3}f_{i+1} - \frac{2}{3}f_{i-1} + \frac{1}{12}f_{i-2}}{\Delta x} + O(\Delta x^4).$$

Error analysis by Taylor series

$$\begin{aligned}f_{i+1} &= f(x = i\Delta x + \Delta x) \\ &= f_i + \Delta x f'_i + \frac{1}{2}\Delta x^2 f''_i + \frac{1}{6}\Delta x^3 f'''_i + \frac{1}{24}\Delta x^4 f''''_i + \dots\end{aligned}$$

Then

$$f_{i+1} - f_{i-1} = 2\Delta x f'_i + \frac{1}{3}\Delta x^3 f'''_i + O(\Delta x^5).$$

But have f'''_i to second order. Substitute for

$$f'_i = \frac{-\frac{1}{12}f_{i+2} + \frac{2}{3}f_{i+1} - \frac{2}{3}f_{i-1} + \frac{1}{12}f_{i-2}}{\Delta x} + O(\Delta x^4).$$

Check expression with $f = 1, x, x^2, x^3, x^4 \rightarrow$ correct 0, 1, 0, 0, 0

Error analysis by Taylor series

$$\begin{aligned}f_{i+1} &= f(x = i\Delta x + \Delta x) \\ &= f_i + \Delta x f'_i + \frac{1}{2}\Delta x^2 f''_i + \frac{1}{6}\Delta x^3 f'''_i + \frac{1}{24}\Delta x^4 f''''_i + \dots\end{aligned}$$

Then

$$f_{i+1} - f_{i-1} = 2\Delta x f'_i + \frac{1}{3}\Delta x^3 f'''_i + O(\Delta x^5).$$

But have f'''_i to second order. Substitute for

$$f'_i = \frac{-\frac{1}{12}f_{i+2} + \frac{2}{3}f_{i+1} - \frac{2}{3}f_{i-1} + \frac{1}{12}f_{i-2}}{\Delta x} + O(\Delta x^4).$$

Check expression with $f = 1, x, x^2, x^3, x^4 \rightarrow$ correct 0, 1, 0, 0, 0

Similarly,

$$f''_i = \frac{-\frac{1}{12}f_{i+2} + \frac{4}{3}f_{i+1} - \frac{5}{2}f_i + \frac{4}{3}f_{i-1} - \frac{1}{12}f_{i-2}}{\Delta x^2} + O(\Delta x^4).$$

b. One-side differencing – used in BC

b. One-side differencing – used in BC

With $O(\Delta x)$ error

$$f'_0 = \frac{f_1 - f_0}{\Delta x} + O(\Delta x),$$

$$f''_0 = \frac{f_2 - 2f_1 + f_0}{\Delta x^2} + O(\Delta x),$$

$$f'''_0 = \frac{f_3 - 3f_2 + 3f_1 - f_0}{\Delta x^3} + O(\Delta x)$$

b. One-side differencing – used in BC

With $O(\Delta x)$ error

$$f'_0 = \frac{f_1 - f_0}{\Delta x} + O(\Delta x),$$

$$f''_0 = \frac{f_2 - 2f_1 + f_0}{\Delta x^2} + O(\Delta x),$$

$$f'''_0 = \frac{f_3 - 3f_2 + 3f_1 - f_0}{\Delta x^3} + O(\Delta x)$$

Error analysis by Taylor series

$$f_1 = f_0 + \Delta x f'_0 + \frac{1}{2} \Delta x^2 f''_0 + O(\Delta x^3).$$

b. One-side differencing – used in BC

With $O(\Delta x)$ error

$$f'_0 = \frac{f_1 - f_0}{\Delta x} + O(\Delta x),$$

$$f''_0 = \frac{f_2 - 2f_1 + f_0}{\Delta x^2} + O(\Delta x),$$

$$f'''_0 = \frac{f_3 - 3f_2 + 3f_1 - f_0}{\Delta x^3} + O(\Delta x)$$

Error analysis by Taylor series

$$f_1 = f_0 + \Delta x f'_0 + \frac{1}{2} \Delta x^2 f''_0 + O(\Delta x^3).$$

Using the first-order expression above for f'_0

$$f'_0 = \frac{-\frac{1}{2} f_2 + 2f_1 - \frac{3}{2} f_0}{\Delta x} + O(\Delta x^2).$$

b. One-side differencing – used in BC

With $O(\Delta x)$ error

$$f'_0 = \frac{f_1 - f_0}{\Delta x} + O(\Delta x),$$

$$f''_0 = \frac{f_2 - 2f_1 + f_0}{\Delta x^2} + O(\Delta x),$$

$$f'''_0 = \frac{f_3 - 3f_2 + 3f_1 - f_0}{\Delta x^3} + O(\Delta x)$$

Error analysis by Taylor series

$$f_1 = f_0 + \Delta x f'_0 + \frac{1}{2} \Delta x^2 f''_0 + O(\Delta x^3).$$

Using the first-order expression above for f'_0

$$f'_0 = \frac{-\frac{1}{2}f_2 + 2f_1 - \frac{3}{2}f_0}{\Delta x} + O(\Delta x^2).$$

Similarly

$$f''_0 = \frac{-f_3 + 4f_2 - 5f_1 + 2f_0}{\Delta x^2} + O(\Delta x^2).$$

c. Non-equispaced points

c. Non-equispaced points

To find k th derivative $f^{(k)}(x_0)$ to $O(\Delta x^l)$
fit polynomial of degree $k + l$ through $k + l + 1$ points $x_0 + \Delta x_i$,

$$f(x_0 + \Delta x_i) = a_0 + a_1 \Delta x_i + a_2 \Delta x_i^2 + \dots + a_{k+l} \Delta x_i^{k+l}.$$

c. Non-equispaced points

To find k th derivative $f^{(k)}(x_0)$ to $O(\Delta x^l)$
fit polynomial of degree $k + l$ through $k + l + 1$ points $x_0 + \Delta x_i$,

$$f(x_0 + \Delta x_i) = a_0 + a_1 \Delta x_i + a_2 \Delta x_i^2 + \dots + a_{k+l} \Delta x_i^{k+l}.$$

Solve for polynomial coefficients a_j , e.g. by MAPLE, then

$$f^{(k)}(x_0) = k! a_k$$

c. Non-equispaced points

To find k th derivative $f^{(k)}(x_0)$ to $O(\Delta x^l)$
fit polynomial of degree $k + l$ through $k + l + 1$ points $x_0 + \Delta x_i$,

$$f(x_0 + \Delta x_i) = a_0 + a_1 \Delta x_i + a_2 \Delta x_i^2 + \dots + a_{k+l} \Delta x_i^{k+l}.$$

Solve for polynomial coefficients a_j , e.g. by MAPLE, then

$$f^{(k)}(x_0) = k! a_k$$

Central differencing on equispaced points \rightarrow one degree accuracy better

c. Non-equispaced points

To find k th derivative $f^{(k)}(x_0)$ to $O(\Delta x^l)$
fit polynomial of degree $k + l$ through $k + l + 1$ points $x_0 + \Delta x_i$,

$$f(x_0 + \Delta x_i) = a_0 + a_1 \Delta x_i + a_2 \Delta x_i^2 + \dots + a_{k+l} \Delta x_i^{k+l}.$$

Solve for polynomial coefficients a_j , e.g. by MAPLE, then

$$f^{(k)}(x_0) = k! a_k$$

Central differencing on equispaced points \rightarrow one degree accuracy better

Splines better than higher order polynomials \rightarrow FEM

Compact 4th order Poisson solver

a. one-dimensional version

Fourth-order differencing for $\phi_i'' = \rho$

$$-\frac{1}{12}\phi_{i+2} + \frac{4}{3}\phi_{i+1} - \frac{5}{2}\phi_i + \frac{4}{3}\phi_{i-1} - \frac{1}{12}\phi_{i-2} = \Delta x^2 \rho_i.$$

Problems: wide molecule, need special form near boundary

Compact 4th order Poisson solver

a. one-dimensional version

Fourth-order differencing for $\phi_i'' = \rho$

$$-\frac{1}{12}\phi_{i+2} + \frac{4}{3}\phi_{i+1} - \frac{5}{2}\phi_i + \frac{4}{3}\phi_{i-1} - \frac{1}{12}\phi_{i-2} = \Delta x^2 \rho_i.$$

Problems: wide molecule, need special form near boundary

Error in 2nd order version

$$\frac{\phi_{i+1} - 2\phi_i + \phi_{i-1}}{\Delta x^2} = \phi_i'' + \frac{1}{6}\Delta x^2 \phi_i'''' + O(\Delta x^4).$$

Compact 4th order Poisson solver

a. one-dimensional version

Fourth-order differencing for $\phi_i'' = \rho$

$$-\frac{1}{12}\phi_{i+2} + \frac{4}{3}\phi_{i+1} - \frac{5}{2}\phi_i + \frac{4}{3}\phi_{i-1} - \frac{1}{12}\phi_{i-2} = \Delta x^2 \rho_i.$$

Problems: wide molecule, need special form near boundary

Error in 2nd order version

$$\frac{\phi_{i+1} - 2\phi_i + \phi_{i-1}}{\Delta x^2} = \phi_i'' + \frac{1}{6}\Delta x^2 \phi_i'''' + O(\Delta x^4).$$

Now $\phi_i'' = \rho_i$ and so

$$\phi_i'''' = \rho_i'' = \frac{\rho_{i+1} - 2\rho_i + \rho_{i-1}}{\Delta x^2} + O(\Delta x^2).$$

Compact 4th order Poisson solver

a. one-dimensional version

Fourth-order differencing for $\phi_i'' = \rho$

$$-\frac{1}{12}\phi_{i+2} + \frac{4}{3}\phi_{i+1} - \frac{5}{2}\phi_i + \frac{4}{3}\phi_{i-1} - \frac{1}{12}\phi_{i-2} = \Delta x^2 \rho_i.$$

Problems: wide molecule, need special form near boundary

Error in 2nd order version

$$\frac{\phi_{i+1} - 2\phi_i + \phi_{i-1}}{\Delta x^2} = \phi_i'' + \frac{1}{6}\Delta x^2 \phi_i'''' + O(\Delta x^4).$$

Now $\phi_i'' = \rho_i$ and so

$$\phi_i'''' = \rho_i'' = \frac{\rho_{i+1} - 2\rho_i + \rho_{i-1}}{\Delta x^2} + O(\Delta x^2).$$

Hence

$$\frac{\phi_{i+1} - 2\phi_i + \phi_{i-1}}{\Delta x^2} = \frac{1}{6}\rho_{i+1} + \frac{2}{3}\rho_i + \frac{1}{6}\rho_{i-1} + O(\Delta x^4).$$

b. two-dimensional version

Use

$$\nabla^2 \rho = \nabla^2 \nabla^2 \phi = \frac{\partial^4 \phi}{\partial x^4} + 2 \frac{\partial^4 \phi}{\partial x^2 \partial y^2} + \frac{\partial^4 \phi}{\partial y^4}.$$

b. two-dimensional version

Use

$$\nabla^2 \rho = \nabla^2 \nabla^2 \phi = \frac{\partial^4 \phi}{\partial x^4} + 2 \frac{\partial^4 \phi}{\partial x^2 \partial y^2} + \frac{\partial^4 \phi}{\partial y^4}.$$

Now

$$\begin{pmatrix} & 1 & \\ 1 & -4 & 1 \\ & 1 & \end{pmatrix} \phi = \Delta x^2 \nabla^2 \phi + \frac{1}{12} \Delta x^4 \left(\frac{\partial^4 \phi}{\partial x^4} + \frac{\partial^4 \phi}{\partial y^4} \right).$$

b. two-dimensional version

Use

$$\nabla^2 \rho = \nabla^2 \nabla^2 \phi = \frac{\partial^4 \phi}{\partial x^4} + 2 \frac{\partial^4 \phi}{\partial x^2 \partial y^2} + \frac{\partial^4 \phi}{\partial y^4}.$$

Now

$$\begin{pmatrix} & 1 & \\ 1 & -4 & 1 \\ & 1 & \end{pmatrix} \phi = \Delta x^2 \nabla^2 \phi + \frac{1}{12} \Delta x^4 \left(\frac{\partial^4 \phi}{\partial x^4} + \frac{\partial^4 \phi}{\partial y^4} \right).$$

and

$$\begin{pmatrix} 1 & & 1 \\ & -4 & \\ 1 & & 1 \end{pmatrix} \phi = 2 \Delta x^2 \nabla^2 \phi + \frac{1}{6} \Delta x^4 \left(\frac{\partial^4 \phi}{\partial x^4} + 6 \frac{\partial^4 \phi}{\partial x^2 \partial y^2} + \frac{\partial^4 \phi}{\partial y^4} \right).$$

b. two-dimensional version

Use

$$\nabla^2 \rho = \nabla^2 \nabla^2 \phi = \frac{\partial^4 \phi}{\partial x^4} + 2 \frac{\partial^4 \phi}{\partial x^2 \partial y^2} + \frac{\partial^4 \phi}{\partial y^4}.$$

Now

$$\begin{pmatrix} & 1 & \\ 1 & -4 & 1 \\ & 1 & \end{pmatrix} \phi = \Delta x^2 \nabla^2 \phi + \frac{1}{12} \Delta x^4 \left(\frac{\partial^4 \phi}{\partial x^4} + \frac{\partial^4 \phi}{\partial y^4} \right).$$

and

$$\begin{pmatrix} 1 & & 1 \\ & -4 & \\ 1 & & 1 \end{pmatrix} \phi = 2 \Delta x^2 \nabla^2 \phi + \frac{1}{6} \Delta x^4 \left(\frac{\partial^4 \phi}{\partial x^4} + 6 \frac{\partial^4 \phi}{\partial x^2 \partial y^2} + \frac{\partial^4 \phi}{\partial y^4} \right).$$

Hence $\frac{2}{3}$ of first + $\frac{1}{6}$ of second

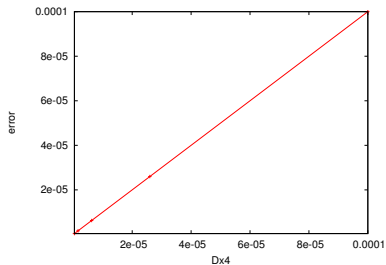
$$\frac{1}{\Delta x^2} \begin{pmatrix} \frac{1}{6} & \frac{2}{3} & \frac{1}{6} \\ \frac{2}{3} & -\frac{10}{3} & \frac{2}{3} \\ \frac{1}{6} & \frac{2}{3} & \frac{1}{6} \end{pmatrix} \phi = \begin{pmatrix} 0 & \frac{1}{12} & 0 \\ \frac{1}{12} & \frac{2}{3} & \frac{1}{12} \\ 0 & \frac{1}{12} & 0 \end{pmatrix} \rho + O(\Delta x^4).$$

Test

Analytic solution

$$\rho = 2\pi^2 \sin \pi x \sin \pi y \quad \text{and} \quad \phi = -\sin \pi x \sin \pi y.$$

with $N = 10, 14, 20, 40$ and 56

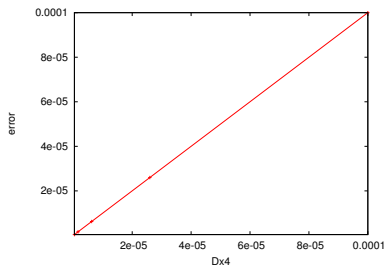


Test

Analytic solution

$$\rho = 2\pi^2 \sin \pi x \sin \pi y \quad \text{and} \quad \phi = -\sin \pi x \sin \pi y.$$

with $N = 10, 14, 20, 40$ and 56



Error decreasing as $0.27\Delta x^4$,
i.e $N = 20$ gives $2 \cdot 10^{-6}$ cf $2 \cdot 10^{-3}$ for 2nd order.

Crandall 4th order for diffusion equation

Similar trick, with cancellation of $\Delta t^2 \frac{\partial^2 u}{\partial t^2}$ with $\frac{1}{6} \Delta x^4 \frac{\partial^4 u}{\partial x^4}$ errors.

Crandall 4th order for diffusion equation

Similar trick, with cancellation of $\Delta t^2 \frac{\partial^2 u}{\partial t^2}$ with $\frac{1}{6} \Delta x^4 \frac{\partial^4 u}{\partial x^4}$ errors.

$$\begin{aligned} u_i^{n+1} + \left(\frac{1}{12} - \frac{\Delta t}{2\Delta x^2} \right) (u_{i+1}^{n+1} - 2u_i^{n+1} + u_{i-1}^{n+1}) \\ = u_i^n + \left(\frac{1}{12} + \frac{\Delta t}{2\Delta x^2} \right) (u_{i+1}^n - 2u_i^n + u_{i-1}^n). \end{aligned}$$

Upwinding

Advection $\mathbf{u} \cdot \nabla \phi$ propagates information in direction \mathbf{u} .

Upwinding

Advection $\mathbf{u} \cdot \nabla \phi$ propagates information in direction \mathbf{u} .

Violated by central differencing

$$u_i \frac{\phi_{i+1} - \phi_{i-1}}{2\Delta x}$$

where if $u_i > 0$ downstream ϕ_{i+1} influences ϕ_i .

Upwinding

Advection $\mathbf{u} \cdot \nabla \phi$ propagates information in direction \mathbf{u} .

Violated by central differencing

$$u_i \frac{\phi_{i+1} - \phi_{i-1}}{2\Delta x}$$

where if $u_i > 0$ downstream ϕ_{i+1} influences ϕ_i .

Correct flow of info by upwinding

$$u \frac{\partial \phi}{\partial x} = \begin{cases} u_i \frac{\phi_i - \phi_{i-1}}{\Delta x} & \text{if } u_i > 0 \\ u_i \frac{\phi_{i+1} - \phi_i}{\Delta x} & \text{if } u_i < 0, \end{cases}$$

Upwinding

Advection $\mathbf{u} \cdot \nabla \phi$ propagates information in direction \mathbf{u} .
Violated by central differencing

$$u_i \frac{\phi_{i+1} - \phi_{i-1}}{2\Delta x}$$

where if $u_i > 0$ downstream ϕ_{i+1} influences ϕ_i .

Correct flow of info by upwinding

$$u \frac{\partial \phi}{\partial x} = \begin{cases} u_i \frac{\phi_i - \phi_{i-1}}{\Delta x} & \text{if } u_i > 0 \\ u_i \frac{\phi_{i+1} - \phi_i}{\Delta x} & \text{if } u_i < 0, \end{cases}$$

But only 1st order accurate, $O(\Delta x)$ errors.

Higher order

One-sided differencing at $O(\Delta x^2)$

$$u \frac{\partial \phi}{\partial x} = \begin{cases} u_i \frac{\frac{3}{2}\phi_i - 2\phi_{i-1} + \frac{1}{2}\phi_{i-2}}{\Delta x} & \text{if } u_i > 0 \\ u_i \frac{-\frac{1}{2}\phi_{i+2} + 2\phi_{i+1} - \frac{3}{2}\phi_i}{\Delta x} & \text{if } u_i < 0, \end{cases}$$

But wide molecule.

Higher order

One-sided differencing at $O(\Delta x^2)$

$$u \frac{\partial \phi}{\partial x} = \begin{cases} u_i \frac{\frac{3}{2}\phi_i - 2\phi_{i-1} + \frac{1}{2}\phi_{i-2}}{\Delta x} & \text{if } u_i > 0 \\ u_i \frac{-\frac{1}{2}\phi_{i+2} + 2\phi_{i+1} - \frac{3}{2}\phi_i}{\Delta x} & \text{if } u_i < 0, \end{cases}$$

But wide molecule.

More compact and nearly upwinding

$$\frac{u}{\Delta x} \begin{pmatrix} 0 & 0 & 0 \\ -1 & 1 & 0 \\ -\frac{1}{2} & 1 & \frac{1}{2} \end{pmatrix} \phi + \frac{v}{\Delta x} \begin{pmatrix} \frac{1}{2} & 0 & 0 \\ 1 & 1 & 0 \\ -\frac{1}{2} & -1 & 0 \end{pmatrix} \phi.$$

$u > 0$ and $v > 0$

Other grids

Geometry of problem \rightarrow polars, other OG coords,

Other grids

Geometry of problem \rightarrow polars, other OG coods, non-OG bad idea

Other grids

Geometry of problem \rightarrow polars, other OG coords, non-OG bad idea

Increased resolution of important small regions

stretched grid $x(\xi)$ and/or $y(\eta)$

Other grids

Geometry of problem \rightarrow polars, other OG coords, non-OG bad idea

Increased resolution of important small regions

stretched grid $x(\xi)$ and/or $y(\eta)$

NB OG. Central differencing on ξ and η better than non-equispaced

Other grids

Geometry of problem \rightarrow polars, other OG coords, **non-OG bad idea**

Increased resolution of important small regions

stretched grid $x(\xi)$ and/or $y(\eta)$

NB OG. Central differencing on ξ and η better than non-equispaced

Can give unnecessary coverage, e.g. away from important corner.

Other grids

Geometry of problem \rightarrow polars, other OG coods, **non-OG bad idea**

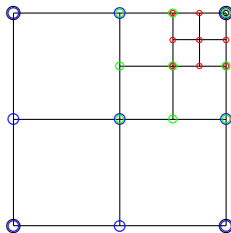
Increased resolution of important small regions

stretched grid $x(\xi)$ and/or $y(\eta)$

NB OG. Central differencing on ξ and η better than non-equispaced

Can give unnecessary coverage, e.g. away from important corner.

Difficult to **match**
different resolutions



but stability

Time-step stability controlled by smallest grid block

but stability

Time-step stability controlled by smallest grid block

Diffusive numerical stability

$$\Delta t < \frac{1}{4} Re \Delta x_{\min}^2,$$

Advection stability

$$\Delta t < (\Delta x / U)_{\min}.$$

but stability

Time-step stability controlled by smallest grid block

Diffusive numerical stability

$$\Delta t < \frac{1}{4} Re \Delta x_{\min}^2,$$

Advection stability

$$\Delta t < (\Delta x / U)_{\min}.$$

Restriction acute for polars

$$\Delta x_{\min} = r_{\min} \Delta \theta_{\min} \quad \text{with} \quad r_{\min} = \Delta r$$

but stability

Time-step stability controlled by smallest grid block

Diffusive numerical stability

$$\Delta t < \frac{1}{4} Re \Delta x_{\min}^2,$$

Advection stability

$$\Delta t < (\Delta x / U)_{\min}.$$

Restriction acute for polars

$$\Delta x_{\min} = r_{\min} \Delta \theta_{\min} \quad \text{with} \quad r_{\min} = \Delta r$$

In infinite domains, bring infinity nearer with stretch such as

$$x = e^{\xi} \quad \text{or} \quad x = \frac{\xi}{1 - \xi}.$$

Conservative forms

Two ideas

- ▶ conservative formulation of governing equation
- ▶ apply to a Finite Volume of Fluids (VoF)

Conservative forms

Two ideas

- ▶ conservative formulation of governing equation
- ▶ apply to a Finite Volume of Fluids (VoF)

Recast Navier-Stokes to

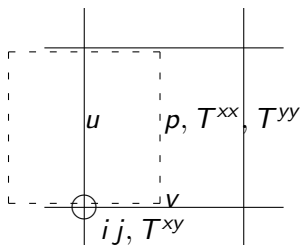
$$\frac{\partial}{\partial t} (\rho \mathbf{u}) + \nabla \cdot \mathbf{T} = 0$$

with total momentum flux

$$\mathbf{T} = \rho \mathbf{u} \mathbf{u} + p \mathbf{I} - 2\mu \mathbf{E}$$

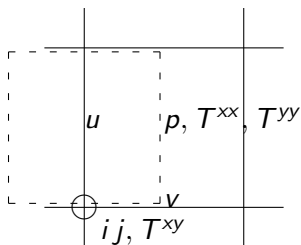
Reynolds stresses, isotropic pressure and viscous stresses

apply to Volume of Fluid on staggered grid



$$\rho u_{ij+\frac{1}{2}}^{n+1} = \rho u_{ij+\frac{1}{2}}^n - \Delta t \left(\frac{T_{i+\frac{1}{2}j+\frac{1}{2}}^{xx} - T_{i-\frac{1}{2}j+\frac{1}{2}}^{xx}}{\Delta x} + \frac{T_{ij+1}^{xy} - T_{ij}^{xy}}{\Delta x} \right).$$

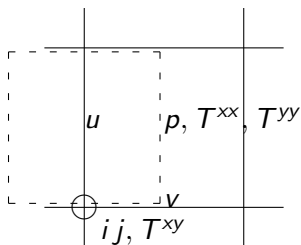
apply to Volume of Fluid on staggered grid



$$\rho u_{ij+\frac{1}{2}}^{n+1} = \rho u_{ij+\frac{1}{2}}^n - \Delta t \left(\frac{T_{i+\frac{1}{2}j+\frac{1}{2}}^{xx} - T_{i-\frac{1}{2}j+\frac{1}{2}}^{xx}}{\Delta x} + \frac{T_{ij+1}^{xy} - T_{ij}^{xy}}{\Delta x} \right).$$

When integrate over a large volume, internal momentum fluxes cancel.

apply to Volume of Fluid on staggered grid



$$\rho u_{ij+\frac{1}{2}}^{n+1} = \rho u_{ij+\frac{1}{2}}^n - \Delta t \left(\frac{T_{i+\frac{1}{2}j+\frac{1}{2}}^{xx} - T_{i-\frac{1}{2}j+\frac{1}{2}}^{xx}}{\Delta x} + \frac{T_{ij+1}^{xy} - T_{ij}^{xy}}{\Delta x} \right).$$

When integrate over a large volume, internal momentum fluxes cancel.

For momentum conservation on whole domain, need e.g. on $x = 0$

$$T_{-\frac{1}{2}j+\frac{1}{2}}^{xx} = T_{\frac{1}{2}j+\frac{1}{2}}^{xx} + T_{0j+1}^{xy} - T_{0j}^{xy},$$

fluxes on staggered grid

Some averaging for inertia terms, but not for pressure and viscous terms

$$\begin{aligned}T_{i+\frac{1}{2}j+\frac{1}{2}}^{xx} &= \rho \left(\frac{u_{i+1j+\frac{1}{2}} + u_{ij+\frac{1}{2}}}{2} \right)^2 + p_{i+\frac{1}{2}j+\frac{1}{2}} - 2\mu \frac{u_{i+1j+\frac{1}{2}} - u_{ij+\frac{1}{2}}}{\Delta x} \\T_{ij}^{xy} &= \rho \left(\frac{u_{ij+\frac{1}{2}} + u_{ij-\frac{1}{2}}}{2} \right) \left(\frac{v_{i+\frac{1}{2}j} + v_{i-\frac{1}{2}j}}{2} \right) \\&\quad - 2\mu \left(\frac{u_{ij+\frac{1}{2}} - u_{ij-\frac{1}{2}}}{\Delta x} + \frac{v_{i+\frac{1}{2}j} - v_{i-\frac{1}{2}j}}{\Delta x} \right) \\T_{i+\frac{1}{2}j+\frac{1}{2}}^{yy} &= \rho \left(\frac{v_{i+\frac{1}{2}j+1} + v_{i+\frac{1}{2}j}}{2} \right)^2 + p_{i+\frac{1}{2}j+\frac{1}{2}} - 2\mu \frac{v_{i+\frac{1}{2}j+1} - v_{i+\frac{1}{2}j}}{\Delta x}.\end{aligned}$$

Use conservative form in non-Cartesian coords

$$\nabla^2 \phi = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial \phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2}$$

better numerically than theoretically equivalent

$$\frac{\partial^2 \phi}{\partial r^2} + \frac{2}{r} \frac{\partial \phi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2}$$

Use conservative form in non-Cartesian coords

$$\nabla^2 \phi = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial \phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2}$$

better numerically than theoretically equivalent

$$\frac{\partial^2 \phi}{\partial r^2} + \frac{2}{r} \frac{\partial \phi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2}$$

Discretisation

$$\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial \phi}{\partial r} \right) \approx \frac{\left(r^2 \frac{\partial \phi}{\partial r} \right)_{i+\frac{1}{2}} - \left(r^2 \frac{\partial \phi}{\partial r} \right)_{i-\frac{1}{2}}}{r_i^2 \Delta r}$$

with

$$\left(r^2 \frac{\partial \phi}{\partial r} \right)_{i+\frac{1}{2}} \approx r_{i+\frac{1}{2}}^2 \frac{\phi_{i+1} - \phi_i}{\Delta r}.$$

Two-phase flows

Volume-of-Fluid or One-Fluid Method
= conservative scheme with $\rho(x)$ and $\mu(x)$

Alternative forms of nonlinear term

$$\begin{aligned}\mathbf{u} \cdot \nabla \mathbf{u} &= \nabla \cdot \mathbf{u} \mathbf{u} && \text{conserves momentum} \\ &= \nabla \frac{1}{2} u^2 - \mathbf{u} \wedge \boldsymbol{\omega} && \text{rotational form} \\ &= \frac{1}{2} \mathbf{u} \cdot \nabla \mathbf{u} + \frac{1}{2} \nabla \cdot \mathbf{u} \mathbf{u} && \text{conserves energy.}\end{aligned}$$

Last called “skew-symmetric” form.

Alternative forms of nonlinear term

$$\begin{aligned}\mathbf{u} \cdot \nabla \mathbf{u} &= \nabla \cdot \mathbf{u} \mathbf{u} && \text{conserves momentum} \\ &= \nabla \cdot \frac{1}{2} u^2 - \mathbf{u} \wedge \boldsymbol{\omega} && \text{rotational form} \\ &= \frac{1}{2} \mathbf{u} \cdot \nabla \mathbf{u} + \frac{1}{2} \nabla \cdot \mathbf{u} \mathbf{u} && \text{conserves energy.}\end{aligned}$$

Last called “skew-symmetric” form.

Scalar product with \mathbf{u}

$$\left(u_i u_j (u_i^{j+1} - u_i^{j-1}) + u_i (u_j^{j+1} u_i^{j+1} - u_j^{j-1} u_i^{j-1}) \right) / 2 \Delta x,$$

subscripts for components and superscripts for location.

On summing across domain, cancellations first–fourth,
second–third