Microstructural studies for rheology

- Micro & macro views
- Einstein viscosity
- Rotations
- Deformations
- Interactions
- Polymers
- Others

Rotations

- Rotation of particles
- Macro stress
- Uni-axial straining
 - Extensional viscosity rods
 - Extensional viscosity disks
- Simple shear
 - Shear viscosity
- Anisotropy
- Brownian rotations
 - Macro stress
 - Viscosities
 - Closures

Rotation of particles - rigid and dilute

Spheroid: axes a, b, b, aspect ratio $r = \frac{a}{b}$.



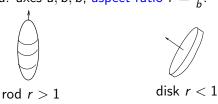




 $\mathsf{disk}\ r<1$

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Direction of axis $\mathbf{p}(t)$, unit vector.

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Stokes flow by Oberbeck (1876). See Lamb. Uses ellipsoidal harmonic function in place of spherical harmonic 1/r

$$\int_{s(\mathbf{x})}^{\infty} \frac{ds'}{\prod_{i=1}^{3} (a_i^2 + s')^{1/2}}, \quad \text{where} \quad \sum_{i=1}^{3} \frac{x_i^2}{a_i^2 + s(\mathbf{x})} = 1.$$

Microstructural evolution equation

$$\frac{D\mathbf{p}}{Dt} = \Omega \times \mathbf{p} + \frac{r^2 - 1}{r^2 + 1} \left[\mathbf{E} \cdot \mathbf{p} - \mathbf{p} (\mathbf{p} \cdot \mathbf{E} \cdot \mathbf{p}) \right]$$

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Flat disks
$$\frac{r^2-1}{r^2+1} \rightarrow -1$$
 i.e. Lower Convective Derivative $\stackrel{\triangle}{A}$

Student Exercise

Show that

$$\mathbf{p}(t) = rac{\mathbf{q}(t)}{|\mathbf{q}(t)|}$$
 with $\dot{\mathbf{q}} = \Omega imes \mathbf{q} + rac{r^2 - 1}{r^2 + 1} \mathbf{E} \cdot \mathbf{q}$

satisfies

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Hence find $\mathbf{p}(t)$ for axisymmetric extensional flow and for simple shear, starting from an arbitrary initial $\mathbf{p}(0)$.

Micro→macro link: stress

$$\overline{\sigma} = -\overline{p}I + 2\mu \mathbf{E} + 2\mu \phi \left[\mathbf{A}(\mathbf{p} \cdot \mathbf{E} \cdot \mathbf{p})\mathbf{p}\mathbf{p} + \mathbf{B}(\mathbf{p}\mathbf{p} \cdot \mathbf{E} + \mathbf{E} \cdot \mathbf{p}\mathbf{p}) + \mathbf{C}\mathbf{E} \right]$$

with A, B, C material constants depending on shape but not size

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$$r o \infty \quad rac{r^2}{2(\ln 2r - rac{3}{2})} \quad rac{6 \ln 2r - 11}{r^2} \quad 2$$
 $r o 0 \quad rac{10}{3\pi r} \quad -rac{8}{3\pi r} \quad rac{8}{3\pi r}$

$$\mathbf{U} = E(x, -\frac{1}{2}y, -\frac{1}{2}z)$$

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Aligns with stretching direction \rightarrow maximum dissipation

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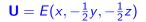


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Aligns with stretching direction \rightarrow maximum dissipation



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Aligns with inflow direction \rightarrow maximum dissipation

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Dilute requires $na^3 \ll 1$, but extension by Batchelor to semi-dilute $\phi \ll 1 \ll \phi r^2$

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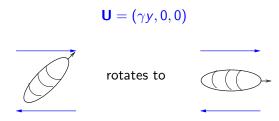
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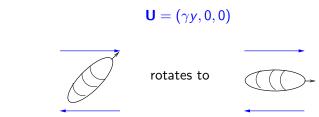
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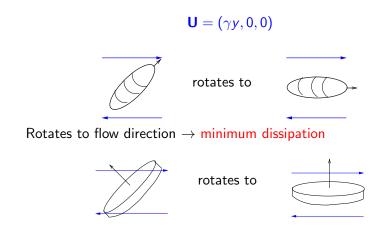
No semi-dilute theory, yet.

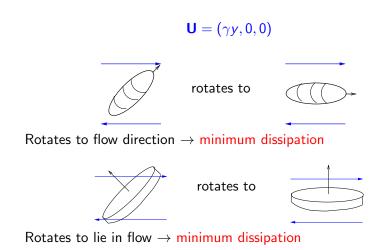
$$\mathbf{U}=(\gamma y,0,0)$$

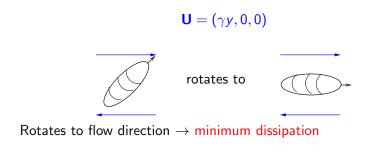




Rotates to flow direction \rightarrow minimum dissipation







Rotates to lie in flow → minimum dissipation

Both Tumble: flip in $1/\gamma$, then align for r/γ $(\delta\theta=1/r$ with $\dot{\theta}=\gamma/r^2)$

rotates to

Effective shear viscosity

Jeffery orbits (1922)

$$\dot{\phi} = \frac{\gamma}{r^2 + 1} (r^2 \cos^2 \phi + \sin^2 \phi)$$

$$\dot{\theta} = \frac{\gamma(r^2 - 1)}{4(r^2 + 1)} \sin 2\theta \sin 2\phi$$

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Solution with orbit constant *C*.

$$\tan \phi = r \tan \omega t$$
, $\omega = \frac{\gamma r}{r^2 + 1}$, $\tan \theta = Cr(r^2 \cos^2 \phi + \sin^2 \phi)^{-1/2}$

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Effective shear viscosity Leal & H (1971)

$$\mu_{\mathrm{shear}}^* = \mu \left(1 + \phi \begin{cases} 0.32 r / \ln r & \mathrm{rods} \\ 3.1 & \mathrm{disks} \end{cases} \right)$$

numerical coefficients depend on distribution across orbits, C.

Alignment gives
$$\mu_{\mathrm{shear}}^* \ll \mu_{\mathrm{ext}}^*$$

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This material anisotropy leads to anisotropy of macro flow.

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Important to Turbulent Drag Reduction

Three measures of concentration of rods

$$\begin{cases} \phi r^2 \doteq n a^3 & \text{for} \quad \mu^*_{\text{ext}} \\ \phi r \doteq n a^2 b & \text{for} \quad \mu^*_{\text{shear}} \\ \phi \doteq n a b^2 & \text{for permeability} \end{cases}$$

Rotary diffusivity: for spheres,

$$D_{\rm rot} = kT/8\pi\mu a^3$$
,

Rotary diffusivity: for spheres, rods

$$D_{\rm rot} = kT / 8\pi \mu a^3, \quad kT / \frac{8\pi \mu a^2}{3(\ln 2r - 1.5)},$$

Rotary diffusivity: for spheres, rods and disks

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Fokker-Plank equation

$$\frac{\partial P}{\partial t} + \nabla \cdot (\dot{\mathbf{p}}P) = D_{\rm rot} \nabla^2 P$$

 $\dot{\mathbf{p}}(\mathbf{p})$ earlier deterministic.

Averaged stress

$$\sigma = -pI + 2\mu E + 2\mu \phi [AE : \langle \mathbf{pppp} \rangle + B(E \cdot \langle \mathbf{pp} \rangle + \langle \mathbf{pp} \rangle \cdot E) + CE + FD_{\text{rot}} \langle \mathbf{pp} \rangle]$$

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Last FD_{rot} term is entropic stress.

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Extra material constant $F = 3r^2/(\ln 2r - 0.5)$ for rods and $12/\pi r$ for disks.

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$$\langle \mathbf{pp} \rangle = \int_{|\mathbf{p}|=1} \mathbf{pp} P \, dp$$

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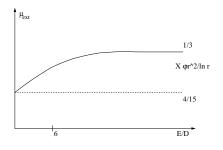
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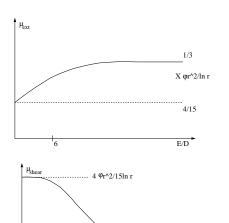
$$\langle \mathsf{pp}
angle = \int_{|\mathsf{p}|=1} \mathsf{pp} P \, dp$$

Solve Fokker-Plank: numerical, weak and strong Brownian rotations



Small strain-hardening

 0.32ϕ r/ln r



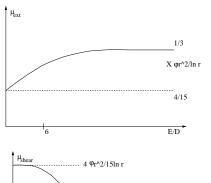
φ r^2/2ln r (D/γ) 1/3

γD

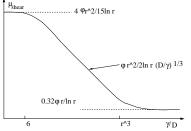
r^3

Small strain-hardening

Large shear-thinning

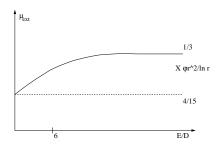


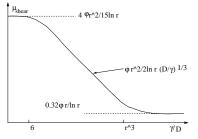
Small strain-hardening



Large shear-thinning

Also $N_1 > 0$, N_2 small < 0.





Small strain-hardening

Orientation effects

Large shear-thinning

Also $N_1 > 0$, N_2 small < 0.

Second moment of Fokker-Plank equation

$$\frac{D}{Dt}\langle \mathbf{pp} \rangle - \Omega \cdot \langle \mathbf{pp} \rangle \langle \mathbf{pp} \rangle \cdot \Omega$$

$$= \frac{r^2 - 1}{r^2 + 1} \left[E \cdot \langle \mathbf{pp} \rangle + \langle \mathbf{pp} \rangle \cdot E - 2 \langle \mathbf{pppp} \rangle : E \right] - 6D_{\text{rot}} \left[\langle \mathbf{pp} \rangle - \frac{1}{3}I \right]$$

Hence this and stress need $\langle \mathbf{pppp} \rangle$, so an infinite hierarchy.

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► Simple 'ad hoc' closure

$$\langle \mathbf{pppp} \rangle : E = \langle \mathbf{pp} \rangle \langle \mathbf{pp} \rangle : E$$

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Better: correct in weak and strong limits

$$= \frac{1}{5} \left[6\langle \mathbf{pp} \rangle \cdot E \cdot \langle \mathbf{pp} \rangle - \langle \mathbf{pp} \rangle \langle \mathbf{pp} \rangle : E - 2I(\langle \mathbf{pp} \rangle^2 : E - \langle \mathbf{pp} \rangle : E) \right]$$

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New idea Brownian fields: simulate many random walks in orientation space for each point of the complex flow.

Rotations

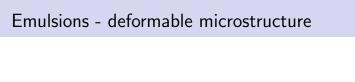
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Deformations

- Emulsions
 - Rupture
 - Theories
 - Numerical
- Flexible thread
- ▶ Double layer



Reviews: Ann. Rev. Fluid Mech. Rallison (1984), Stone (1994)

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► Dilute – single drop, volume $\frac{4\pi}{3}a^3$

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- $T = \text{surface tension (in rheology } \sigma \text{ and } \gamma \text{ not possible)}$

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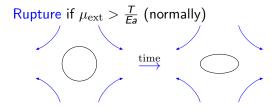
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Emulsions - deformable microstructure

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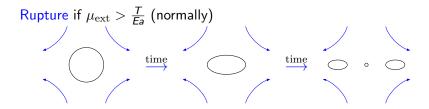
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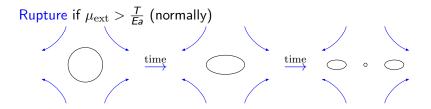
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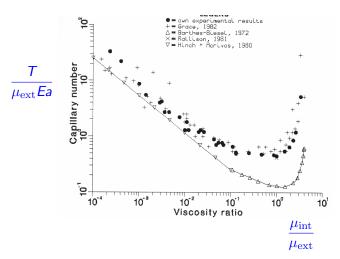
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Irreversible reduction in size to $a_* = T/\mu_{\rm ext} E$, as coalescence very slow.

Rupture in shear flow



Experiments: de Bruijn (1989) (=own), Grace (1982)

Theories: Barthes-Biesel (1972), Rallison (1981), Hinch & Acrivos (1980)

Too slippery.

Too slippery. Become long and thin. Rupture if

$$\mu_{
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m ext}/\mu_{
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ight)^{1/6} & ext{extension} \end{cases}$$

but tip-streaming with mobile surfactants (makes rigid end-cap)

$$\mu_{\rm ext} E > \frac{T}{a} 0.56$$

Rupture difficult is simple shear if $\mu_{
m int} > 3 \mu_{
m ext}$

▶ If internal very viscous ($\mu_{\rm int} \gg \mu_{\rm ext}$),

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 - ▶ then deforms more.
 - if deformed, rotates more slowly in stretching quadrant,
 - if more deformed, rotates more slowly, so deforms even more, etc etc
- until can rupture when $\mu_{\rm int} \leq 3\mu_{\rm ext}$

Small ellipsoidal deformation

$$r = a(1 + \mathbf{x} \cdot \mathbf{A}(t) \cdot \mathbf{x} + \text{higher orders})$$

Small ellipsoidal deformation

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Stokes flow with help of computerised algebra manipulator

$$\frac{D\mathbf{A}}{Dt} - \Omega \cdot \mathbf{A} + \mathbf{A} \cdot \Omega = 2k_1 \mathbf{E} + k_5 (\mathbf{A} \cdot \mathbf{E} + \mathbf{E} \cdot \mathbf{A}) + \dots - \frac{T}{\mu_{\text{ext}} a} (k_2 \mathbf{A} + k_6 (\mathbf{A} \cdot \mathbf{A}) + \dots)$$

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$$\begin{split} \sigma &= -p\mathbf{I} + 2\mu_{\mathrm{ext}}\mathbf{E} + 2\mu_{\mathrm{ext}}\phi \big[k_{3}\mathbf{E} + k_{7}(\mathbf{A}\cdot\mathbf{E} + \mathbf{E}\cdot\mathbf{A}) + \dots \\ &- \frac{T}{\mu_{\mathrm{ext}}a}(k_{4}\mathbf{A} + k_{8}(\mathbf{A}\cdot\mathbf{A}) + \dots \big] \end{split}$$

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with k_n depending on viscosity ratio, $\lambda = \mu_{\rm int}/\mu_{\rm ext}$,

$$k_1 = \frac{5}{2(2\lambda+3)},$$
 $k_2 = \frac{40(\lambda+1)}{(2\lambda+3)(19\lambda+16)}$
 $k_3 = \frac{5(\lambda-1)}{3(2\lambda+3)},$ $k_4 = \frac{4}{2\lambda+3}$

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 k_1 inefficiency of rotating by straining

Inefficiency of rotating by straining

Student Exercise

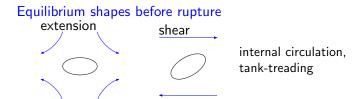
Consider the constitutive equation

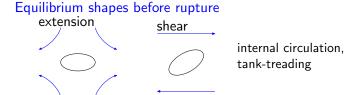
$$\sigma = -pI + 2\mu_0 E + GA$$

$$\frac{DA}{Dt} - \Omega \cdot A + A \cdot \Omega - \alpha (E \cdot A + A \cdot E) = -\frac{1}{\tau} (A - I),$$
in flow $u = (\Omega + E) \cdot x$.

Solve for σ in steady simple shear, finding the shear viscosity and normal stress differences.

Find the condition on the parameters for the shear stress to be a monotonic increasing function of the shear-rate (non-shear-banding).





Rheology before rupture

Small strain-hardening, small shear-thinning, $N_1 > 0$, $N_2 < 0$.



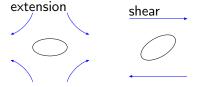
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Repeated rupture leaves $\mu^* \cong \text{constant}$.

Einstein: independent of size of particle, just depends on ϕ .

Equilibrium shapes before rupture



internal circulation, tank-treading

Rheology before rupture

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Form of constitutive equation

$$rac{d}{dt}({
m state})$$
 & σ linear in **E** & $rac{T}{\mu_{
m ext} a}$

Numerical studies: boundary integral method

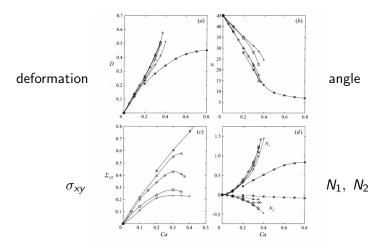
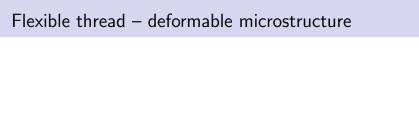


Figure 12. Steady-state results as a function of capillary number for $\phi = 10^{9}$ s; (a) average steady-state drop deformation, (b) do pro orientation, (c) shear stress contributions, and (d) contribution of drops to normal stresses; first normal stress difference (colid curves,) second normal stress difference (dashed curves); $\lambda = 0$ (+), $\lambda = 0$ (2), $\lambda = 0$ (1), $\lambda = 0$ (1), $\lambda = 0$ (2), $\lambda = 0$ (1), $\lambda = 0$ (2), $\lambda = 0$ (1), $\lambda = 0$ (2), $\lambda = 0$ (3), $\lambda = 0$ (1), $\lambda = 0$ (1), $\lambda = 0$ (2), $\lambda = 0$ (3), $\lambda = 0$ (1), $\lambda = 0$ (3), $\lambda = 0$ (1), $\lambda = 0$ (2), $\lambda = 0$ (3), $\lambda = 0$ (3), $\lambda = 0$ (3), $\lambda = 0$ (3), $\lambda = 0$ (4), $\lambda = 0$ (3), $\lambda = 0$ (3), $\lambda = 0$ (3), $\lambda = 0$ (3), $\lambda = 0$ (4), $\lambda = 0$ (3), $\lambda = 0$ (4), $\lambda = 0$ (3), $\lambda = 0$ (4), $\lambda = 0$ (3), $\lambda = 0$ (3), $\lambda = 0$ (4), $\lambda = 0$ (4), $\lambda = 0$ (3), $\lambda = 0$ (4), $\lambda = 0$ (4), $\lambda = 0$ (3), $\lambda = 0$ (4), $\lambda = 0$ (3), $\lambda = 0$ (4), $\lambda = 0$ (4), $\lambda = 0$ (4), $\lambda = 0$ (4), $\lambda = 0$ (5), $\lambda = 0$ (6), $\lambda = 0$ (7), $\lambda = 0$ (8), $\lambda = 0$ (8),

Different λ . No rupture for $\lambda = 5$ (*)



Flexible thread – deformable microstructure

Position $\mathbf{x}(s,t)$, arc length s, tension T(s,t)

Flexible thread - deformable microstructure

Position $\mathbf{x}(s,t)$, arc length s, tension T(s,t)Slender-body theory with 2:1 drag $\perp:\parallel$, S.Ex

$$\dot{\mathbf{x}} = \mathbf{x} \cdot \nabla \mathbf{U} + T' \mathbf{x}' + \frac{1}{2} T \mathbf{x}''$$

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 and $T = 0$ at ends

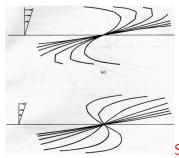
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Snap straight

Electrical double layer on isolated sphere

- another deformable microstructure

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- ightharpoonup very small change in Einstein $\frac{5}{2}$.

Deformations

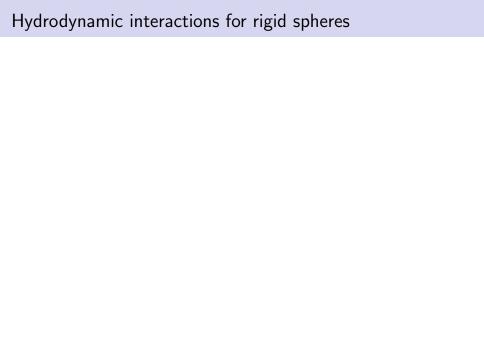
- Emulsions
 - Rupture
 - Theories
 - Numerical
- Flexible thread
- ▶ Double layer

Microstructural studies for rheology

- Micro & macro views
- Einstein viscosity
- Rotations
- Deformations
- Interactions
- Polymers
- Others

Interactions

- Hydrodynamic
 - Dilute
 - Experiments
 - Numerical
- ► Electrical double-layer
 - Concentrated
- van der Waals
- Fibres
- Drops
 - Numerical



Hydrodynamic: difficult long-ranged

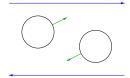
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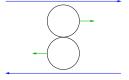
Rigid spheres : two bad ideas

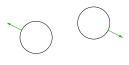
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Dilute – between pairs (mostly)



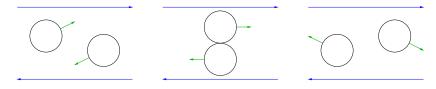




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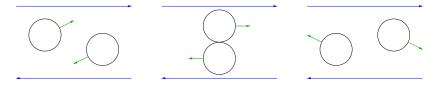


Reversible (spheres + Stokes flow) \rightarrow return to original streamlines

Hydrodynamic: difficult long-ranged

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Dilute – between pairs (mostly)



Reversible (spheres + Stokes flow) \rightarrow return to original streamlines But minimum separation is $\frac{1}{2}\,10^{-4}$ radius \rightarrow sensitive to roughness (typically 1%) when do not return to original streamlines.

Divergent integral from $\nabla \mathbf{u} \sim \frac{1}{r^3}$

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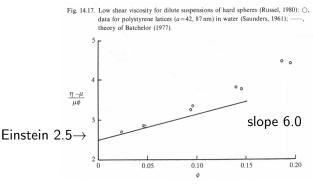
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Small strain-hardening, small shear-thinning

Test of Batchelor ϕ^2 result

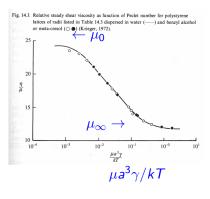
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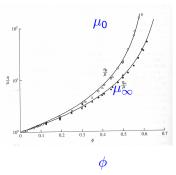


Russel, Saville, Schowalter 1989

Experiments – concentrated

Effective viscosities in shear flow



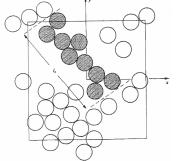


Russel, Saville, Schowalter 1989

- (mostly) pairwise additive hydrodynamics

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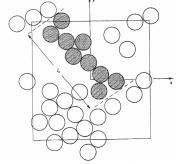
Jamming/locking – clusters across the compressive quadrant



Brady & Bossis (1985)

- (mostly) pairwise additive hydrodynamics

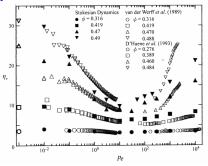
Jamming/locking – clusters across the compressive quadrant



Brady & Bossis (1985)

Fragile clusters if include soft repulsion or Brownian motion

Effective viscosity in shear flow



Foss & Brady (2000)

'Stokesian Dynamics' Brady & Bossis Ann. Rev. Fluid Mech. (1988)

$$6\mu\mu a\gamma r_* = \frac{\epsilon \zeta^2 a^2 \kappa}{r_*} e^{-\kappa (r_* - 2a)}$$

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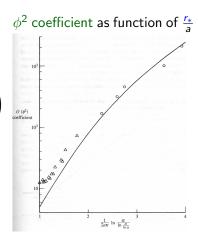
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$$\left(\frac{r_*}{a}\right)^5 = \text{velocity} \quad \gamma r_* \\ \times \text{ force distance} \quad r_* \\ \times \text{ volume} \quad \phi \left(\frac{r_*}{a}\right)^3$$

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Experiments – concentrated

Stress as function of shear-rate at different pH. Suspension of $0.33\mu m$ aluminium particles at $\phi = 0.3$

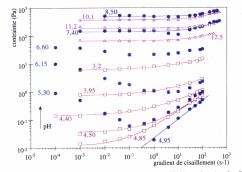


Fig.3 : Courbes d'écoulement de suspensions d'alumine P772SB, en fonction du pH, ϕ_v =0,30.

Ducerf (Grenoble PhD 1992)

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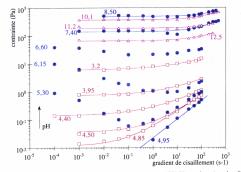


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Note yield stress very sensitive to pH

Interactions – van der Waals

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Possible model of size of flocs R

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Breakdown of structure in rheology $\mu(\gamma)$

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Disk not random if $\phi \frac{1}{r} > 1$.

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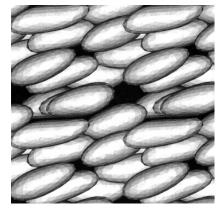
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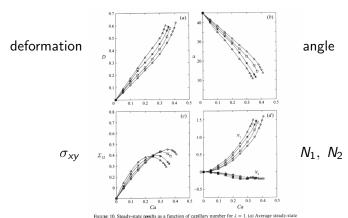
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- ▶ Deformed shape has lower collision cross-section so 'dilute' at $\phi = 0.3$, blood works!

Numerical studies: boundary integral method



 $\phi=$ 0.3, $\textit{Ca}=\mu_{\rm ext}\gamma a/T=$ 0.3 $\lambda=$ 1, $\gamma t=$ 10, 12 drops, each 320 triangles.

Numerical studies: boundary integral method 3

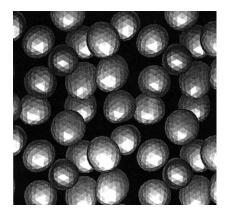


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 $\lambda = 1$, different $\phi = 0, 0.1, 0.2, 0.3$. Effectively dilute at $\phi = 0.3$.

Numerical studies: boundary integral method 4

Reduced cross-section for collisions



into flow

Interactions

- Hydrodynamic
 - Dilute
 - Experiments
 - Numerical
- ► Electrical double-layer
 - Concentrated
- van der Waals
- Fibres
- Drops
 - Numerical

- ► Micro & macro views
- Einstein viscosity
- Rotations
- Deformations
- Interactions
- Polymers
- Others